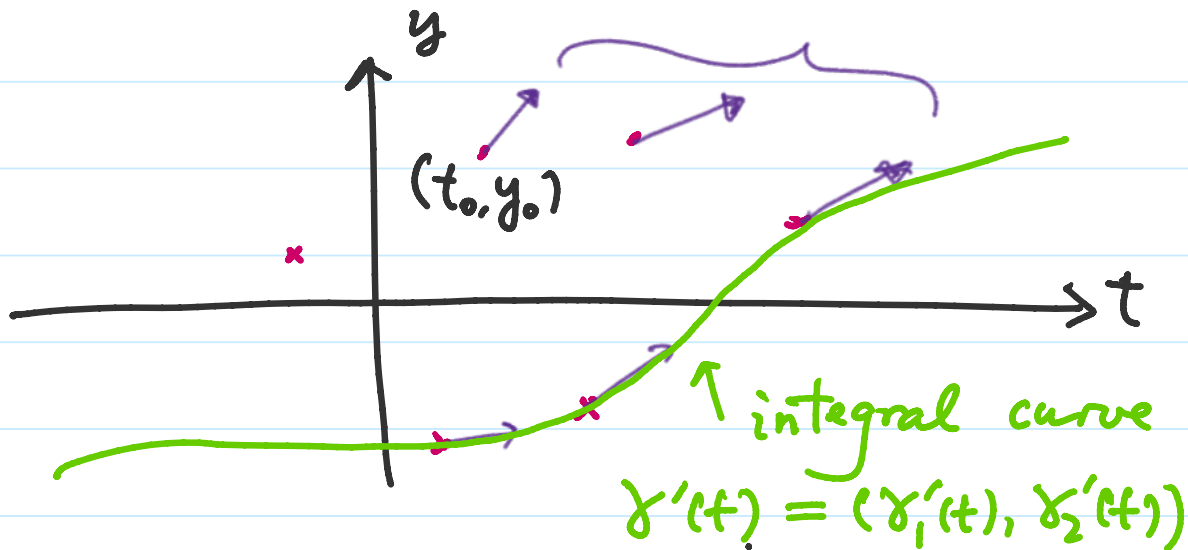


Lecture 3:

11-09-18

§ Geometric view : $y' = f(t, y)$

The vector $(1, f(t, y))$ at each point (t, y_0) is put together to give a vector field.



- Def:
- A vector field $v(t, y)$ is an association of a vector $v(t, y) = (v_1(t, y), v_2(t, y))$ for each point (t, y) .
 - $\gamma(s)$ is an integral curve of v if

$$\gamma'(s) = v(\gamma(s))$$

Prop: $y(t)$ is a solution to $y' = f(t, y)$

\iff its graph $\gamma(t) := (t, y(t))$ is an integral curve for the vector field $v(t, y) = (1, f(t, y))$

Separable equation: (for non-linear equation).

Ex: IVP:
$$\begin{cases} y'(t) = \frac{\sin(t)}{1-y^2} \\ y(t_0) = y_0. \end{cases}$$

First rewrite: $(1-y^2) y' = \sin(t)$

Idea: $(y - \frac{1}{3}y^3)' = (1-y^2)y'$
by chain rule.

Hence:

$$y - \frac{1}{3}y^3 = -\cos(t) + C.$$

Initial value:

$$y_0 - \frac{1}{3}y_0^3 = -\cos(t_0) + C.$$

\Rightarrow solution to IVP

$$y - \frac{1}{3}y^3 = \cos(t_0) - \cos(t) + y_0 - \frac{1}{3}y_0^3$$

we call it an implicit solution to the IVP.

\uparrow because of non-linearity

Rk: We have to use implicit function theorem to solve for y as function of t .

Def:

A first order ODE is called separable if it can be rewritten as

$$M(t) + N(y) \frac{dy}{dt} = 0.$$

Idea: suppose we have anti-derivatives

$$m'(t) = M, \quad n'(t) = N.$$

\Rightarrow we can write

$$\frac{d}{dt} (m(t) + n(y(t))) = 0$$

$\Rightarrow m(t) + n(y(t)) = c$ is an implicit general solution.

• Suppose we look for IVP

then we have

$$m(t_0) + n(y_0) = c$$

$$\Rightarrow n(y(t)) - n(y_0) = m(t_0) - m(t)$$

Example: $y' = p(t)y$ (assume $y \neq 0$)

$$\Rightarrow \underbrace{-p(t)}_{M(t)} + \underbrace{\frac{1}{y} \frac{dy}{dt}}_{N(t)} = 0$$

$$\Rightarrow \log|y(t)| - \log|y_0| = \int_t^{t_0} -p(s) ds$$

$$\Rightarrow y(t) = y_0 e^{\int_{t_0}^t p(s) ds}$$

§ Exact equation:

Recall: We have solve separable equation of the type

$$M(t) + N(y) \frac{dy}{dt} = 0.$$

find $m'(t) = M(t)$, $n'(y) = N(y)$

What if we have

$$M(t, y) + N(t, y) \frac{dy}{dt} = 0 \quad ?$$

Idea: We look for function $\gamma(t, y)$ s.t.

$$\frac{\partial \gamma}{\partial t} = M, \quad \frac{\partial \gamma}{\partial y} = N$$

← Def: Exact equation

separable \Rightarrow
equation

If such γ exist:

We can write

$$\frac{\partial \gamma}{\partial t} \frac{dt}{dt} + \frac{\partial \gamma}{\partial y} \frac{dy}{dt} = 0.$$

$$\text{Chain rule} \Rightarrow \frac{d}{dt} (\gamma(t, y(t))) = 0$$

$$\text{Hence we have } \gamma(t, y(t)) = c$$

Suppose we have the initial condition $y(t_0) = y_0$.

\Rightarrow

$$\gamma(t, y(t)) \equiv \gamma(t_0, y_0)$$

Example:

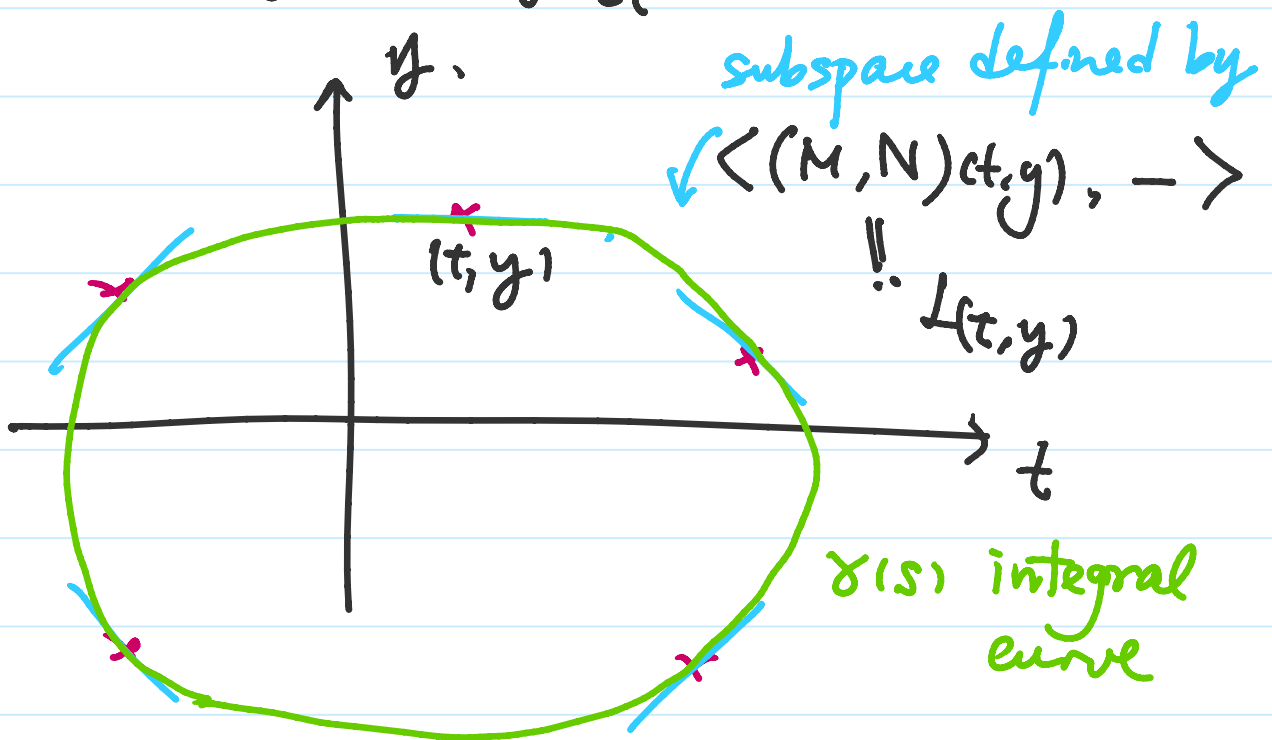
$$M(t, y) = y \cos(ty), \quad N(t, y) = t \cos(ty).$$

We can choose $\gamma = \sin(ty) + a \in \mathbb{R}$.

$$\text{General solution: } \sin(ty(t)) = c.$$

Geometric viewpoint For exact equation:

$$M(t, y) + N(t, y) \frac{dy}{dt} = 0$$



Def: • A direction field is an association of 1-dimensional subspace $L(t, y) \subseteq \mathbb{R}^2$ for each point (t, y) .

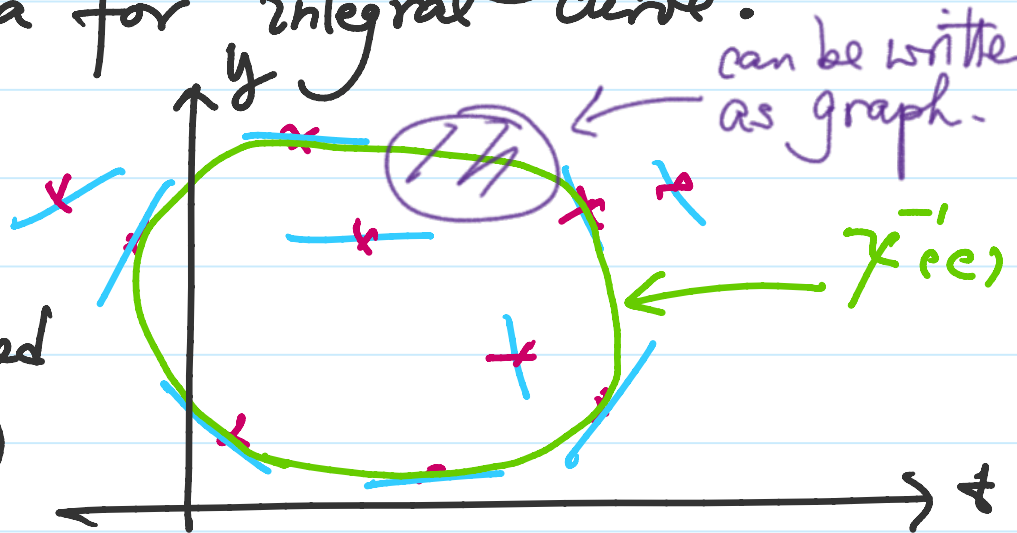
$\gamma(s) = (\gamma_1(s), \gamma_2(s))$ is an integral curve

if $\gamma'(s) \in L_{\gamma(s)}$ or $M\gamma_1' + N\gamma_2' = 0.$

Prop: $y(t)$ solve $M(t, y) + N(t, y) \frac{dy}{dt} = 0$
 \Leftrightarrow its graph $\gamma(t) = (t, y(t))$ is
 an integral curve.

Rk: Indeed we are solving for implicit
 formula for integral curve:
 can be written
 as graph.

- Direction field defined by (M, N)



it is exact $\Rightarrow \exists \gamma$ s.t. $\frac{\partial \gamma}{\partial t} = M, \frac{\partial \gamma}{\partial y} = N$

Hence: The level set
 $\gamma^{-1}(c)$ is an implicit integral curve

We are actually solve for the level set!

- When $\gamma^{-1}(c)$ can be parametrized as a graph $(t, y(t))$, it gives a sol.

Question: When is an equation $M(t,y) + N(t,y) \frac{dy}{dt}$ exact?

Assumption: $M, N, \frac{\partial M}{\partial y}, \frac{\partial N}{\partial t}$ defined on $R = (a,b) \times (c,d)$ and continuous
(*)

Necessary condition: if $M = \frac{\partial \psi}{\partial t}$, $N = \frac{\partial \psi}{\partial y}$

$$\frac{\partial M}{\partial y} = \frac{\partial^2 \psi}{\partial y \partial t} = \frac{\partial^2 \psi}{\partial t \partial y} = \frac{\partial N}{\partial t}.$$

i.e. $\boxed{\frac{\partial M}{\partial y} = \frac{\partial N}{\partial t}}$

Thm: 1. $M(t,y) + N(t,y) \frac{dy}{dt}$ exact $\iff \frac{\partial M}{\partial y} = \frac{\partial N}{\partial t}$
under the assumption (*) above

Pf: $\Rightarrow \because \frac{\partial^2 \psi}{\partial t \partial y} = \frac{\partial^2 \psi}{\partial y \partial t}.$

\Leftarrow) We want to construct such a ψ satisfying

$$\frac{\partial \psi}{\partial t} = M, \quad \frac{\partial \psi}{\partial y} = N.$$

$$\text{Let } Q(t,y) = \int_{t_0}^t M(s,y) ds$$

$$\Rightarrow \psi(t,y) = Q(t,y) + h(y)$$

$$(\because \frac{\partial}{\partial t} (\psi - Q) = 0 \Rightarrow \psi - Q \text{ function of } y)$$

taking derivatives in y -direction.

$$\frac{\partial y}{\partial t} = \frac{\partial}{\partial y} \int_{t_0}^t M(s, y) ds + \frac{dh}{dy}$$

$$N = \frac{\partial}{\partial y} \int_{t_0}^t M(s, y) ds + \frac{dh}{dy}$$

$$\frac{dh}{dy} = N - \frac{\partial}{\partial y} \int_{t_0}^t M(s, y) ds$$

independent of t !

this should be independent of t .

$$\begin{aligned} & \frac{\partial}{\partial t} \left(N - \frac{\partial}{\partial y} \int_{t_0}^t M(s, y) ds \right) \\ &= \frac{\partial N}{\partial t} - \frac{\partial}{\partial t} \frac{\partial}{\partial y} \int_{t_0}^t M(s, y) ds \\ &= \frac{\partial N}{\partial t} - \frac{\partial}{\partial y} \frac{\partial}{\partial t} \int_{t_0}^t M(s, y) ds \\ &= \frac{\partial N}{\partial t} - \frac{\partial N}{\partial t} = 0. \end{aligned}$$

$$\Rightarrow h(y) = \int_{y_0}^y N(t_0, w) dw - \int_{y_0}^y \frac{\partial}{\partial w} \int_{t_0}^{t_0} M(s, w) ds dw$$

+ ~~e~~ ← Not important

$$\chi(t, y) = \int_{t_0}^t M(s, y) ds + \int_{y_0}^y N(t_0, w) dw$$

Rk: • This result depends heavily on the fact that $R = (a, b) \times (c, d)$ is simply connected

Example: $M(t, y) = y \cos(t) + 2te^y$
 $N(t, y) = \sin(t) + t^2e^y - 1.$

$$\frac{\partial M}{\partial y} = \cos(t) + 2te^y, \quad \frac{\partial N}{\partial t} = \cos(t) + 2te^y$$

it is exact, and we need to solve for γ

$$\gamma(t, y) = \int_{t_0}^t M(s, y) ds + \int_{y_0}^y N(t_0, w) dw$$

$$= \int_{t_0}^t (y \cos s + 2se^y) ds + \int_{y_0}^y (\sin(t_0) + t_0^2 e^w - 1) dw$$

$$= y \sin(s) + s^2 e^y \Big|_{t_0}^t + (\sin(t_0) - 1)w + t_0^2 e^w \Big|_{y_0}^y$$

$$= y \sin(t) + t^2 e^y + \underbrace{(y_0 - y) - y_0 \sin(t_0) - t_0^2 e^{y_0}}_{\text{constant.}}$$

take $\gamma = y \sin(t) + t^2 e^y - y$

We have general implicit solution is given by
 $y(t) \sin(t) + t^2 e^{y(t)} - y(t) = c.$

Counter example:

$R = \mathbb{R}^2 \setminus \{0\}$, then this is NOT true

$$\text{we let } M(t,y) = \frac{-y}{t^2+y^2}, \quad N(t,y) = \frac{+t}{t^2+y^2}$$

then we have

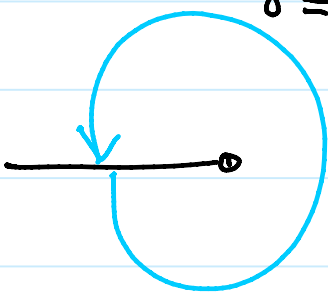
$$\frac{\partial M}{\partial y} = -\frac{t^2+y^2-2y^2}{t^2+y^2} = \frac{y^2-t^2}{t^2+y^2}$$

$$\frac{\partial N}{\partial t} = -\frac{t^2-y^2}{t^2+y^2} = \frac{\partial M}{\partial y}.$$

But $\nexists \gamma$ s.t. $\frac{\partial \gamma}{\partial t} = M$, $\frac{\partial \gamma}{\partial y} = N$.

Reason: suppose we use polar coordinate

$\gamma = (t(s), y(s)) = (r, \theta)$ and let



$\gamma(s)$: a counter-clockwise circle

check: $\frac{\partial \theta}{\partial t} = M$, $\frac{\partial \theta}{\partial y} = N$.

therefore: $\lim_{\epsilon \rightarrow 0} \int_{0+\epsilon}^{2\pi-\epsilon} \left(M \frac{dt}{ds} + N \frac{dy}{ds} \right) ds$

$$= \lim_{\epsilon \rightarrow 0} \int_{0+\epsilon}^{2\pi-\epsilon} \left(\theta(t(s), y(s)) \right)' ds = 2\pi$$

However, if we have such a γ s.t.

$$\frac{\partial \gamma}{\partial t} = M, \quad \frac{\partial \gamma}{\partial y} = N$$

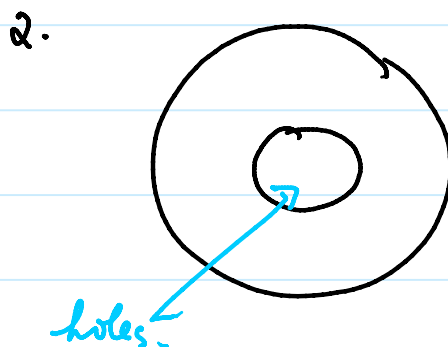
$$\begin{aligned} \Rightarrow \int_0^{2\pi} \left(M \frac{dt}{ds} + N \frac{dy}{ds} \right) ds &= \int_0^{2\pi} \left(\gamma(t(s), y(s)) \right)' ds \\ &= \gamma(t(2\pi), y(2\pi)) - \gamma(t(0), y(0)) = 0. \end{aligned}$$

$$(\because t(2\pi) = t(0), \quad y(2\pi) = y(0).)$$

Hence existence of such γ leads to a contradiction

Roughly: simply connected domain $D \subseteq \mathbb{R}^2$
is those without "holes"

Ex: (non-simply connected)



Extra story: $\mathcal{K} = \left\{ (M, N) \mid \begin{array}{l} M, N: D \rightarrow \mathbb{R} \text{ smooth fcn} \\ \text{satisfying } \frac{\partial M}{\partial y} = \frac{\partial N}{\partial t} \end{array} \right\}$

\mathbb{R} -vector space: $a(M_1, N_1) + (M_2, N_2) = (aM_1 + M_2, aN_1 + N_2)$

we let $\mathcal{R}^0 = \left\{ \gamma \mid \gamma: D \rightarrow \mathbb{R} \text{ smooth fcn} \right\}$

then we can define a linear map d

$$d: \Omega^0 \longrightarrow K$$

$$d(\gamma) := \left(\underbrace{\frac{\partial \gamma}{\partial t}}_M, \underbrace{\frac{\partial \gamma}{\partial y}}_N \right)$$

then we have $H^1(D) := \frac{K}{d\Omega^0}$ be the quotient vector space

one can show:

$$D = \text{[disk with 2 holes]} \Rightarrow \dim(H^1(D)) = 2.$$

$$D = \text{[disk with } k \text{ holes]} \Rightarrow \dim(H^1(D)) = k.$$

in other words, it is an invariant detect
of holes in D